

## Supplemental Figures



Figure S1. Experimental vehicle with lightbar attached.

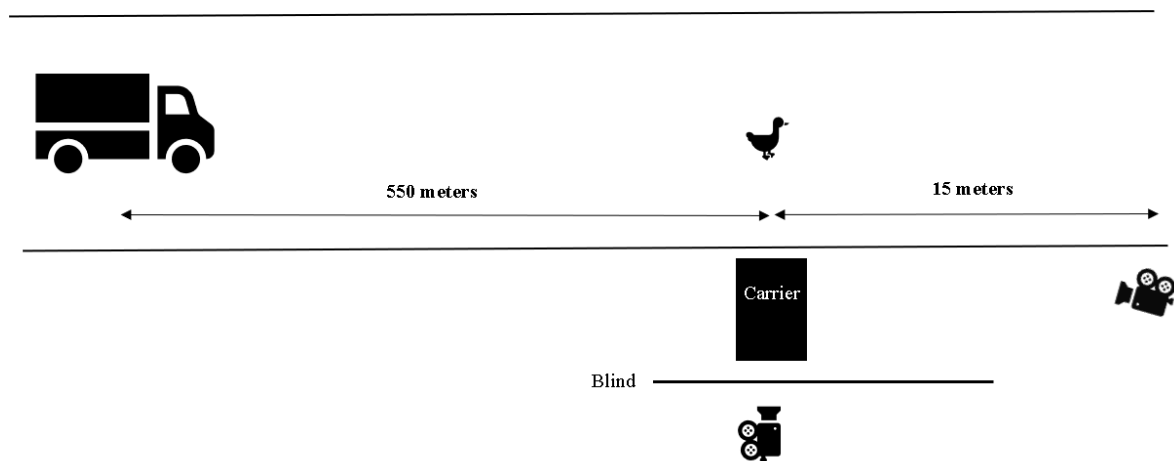


Figure S2. The location of the vehicle, mallard, and cameras at the beginning of an approach in the field.

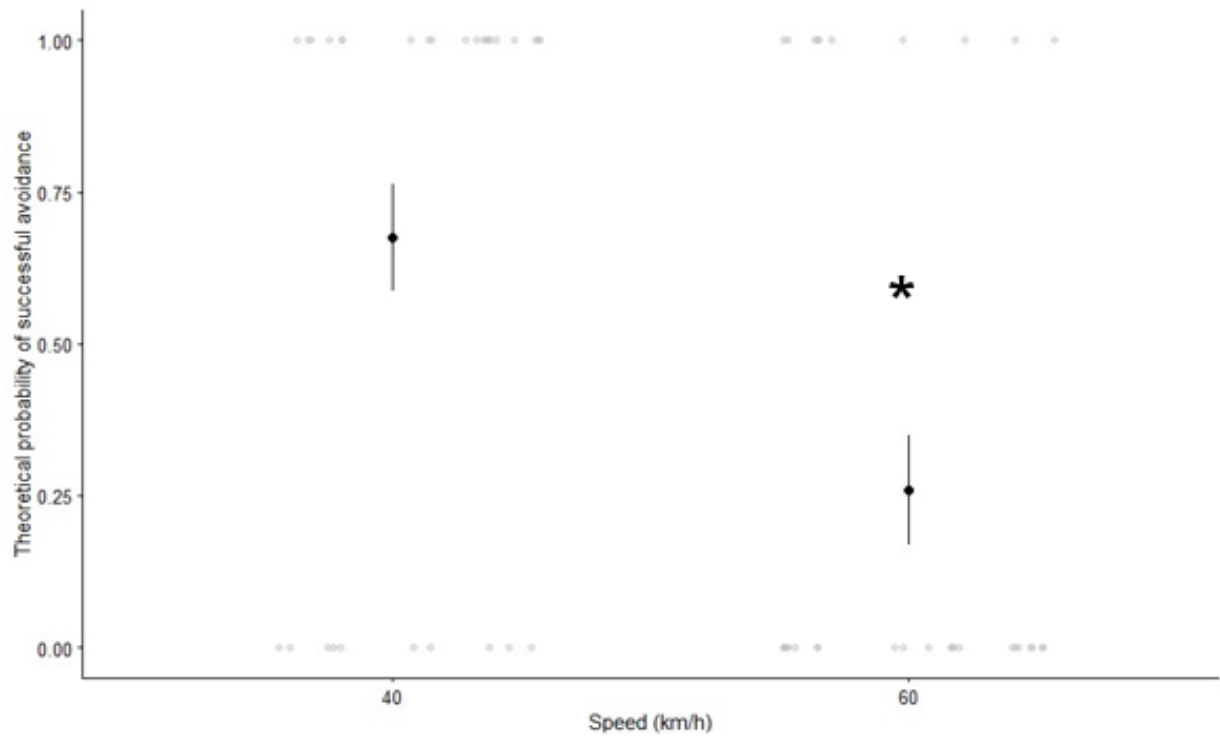


Figure S3. Probability of a mallard's theoretical successful avoidance of the vehicle ( $TTC > 1.0$  s) at two experimental speeds during field vehicle approaches.